

Les Houches

Physics of Star Formation

February 12-23, 2024

brief theoretical introduction

— basic equations —

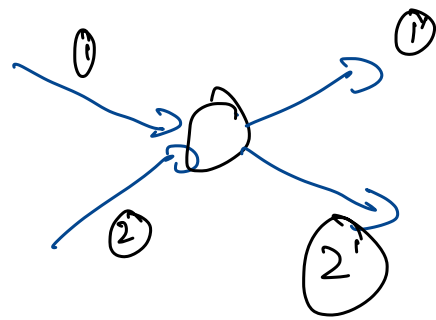
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MOTIVATION OF BASIC EQUATIONS

* equations of hydrodynamics

* reflect conservation laws; these in turn reflect symmetries in fundamental processes;
fully elastic scattering on particle level



five conserved quantities

1) mass

2) - 4) momentum

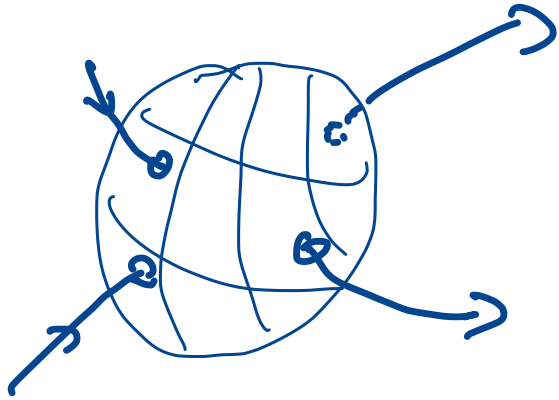
5) energy

* formulation as conservation laws

$$\frac{\partial}{\partial t} [\text{quantity}] + \nabla \cdot [\text{flux of quantity}] = 0$$

in the absence of collision terms

$$= \cancel{[\text{collision term}]}$$



* there are two approaches

[quantity] per unit volume

↳ density [cm^{-3}]

[quantity] per unit mass

↳ specific quantity [g^{-1}]

* conservation of mass:

↳ continuity equation

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{v}) = 0 \quad \textcircled{1}$$

sometimes this better formulated in index notation

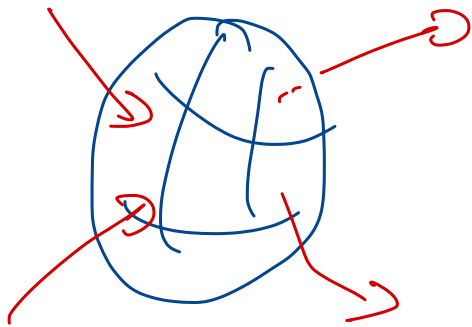
$$\left[\begin{array}{l} \text{Einstein's sum convention} \\ \partial_i v_i = \sum_{i=1}^3 \partial_i v_i = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \end{array} \right]$$

$$\partial_t \rho + \partial_i (\rho v_i) = 0$$

$$\partial_t \mathcal{L} + \underbrace{\partial_i \mathcal{L} v_i}_{\text{product rule}} = \partial_t \mathcal{L} + (\partial_i \mathcal{L}) v_i + \mathcal{L} (\partial_i v_i) = 0$$

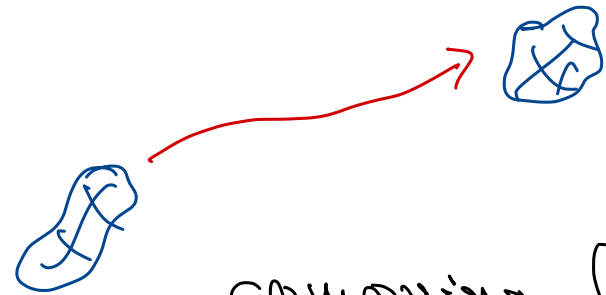
$$\Downarrow \quad \boxed{\frac{\partial \mathcal{L}}{\partial t} + \vec{v} \cdot \vec{\nabla} \mathcal{L} = -\mathcal{L} \vec{\nabla} \cdot \vec{v}} \quad \textcircled{1} \quad \rightarrow \quad \frac{d\mathcal{L}}{dt} = -\mathcal{L} \vec{\nabla} \cdot \vec{v}$$

* difference between comoving and fixed coordinates:



fixed frame

Eulerian point of view

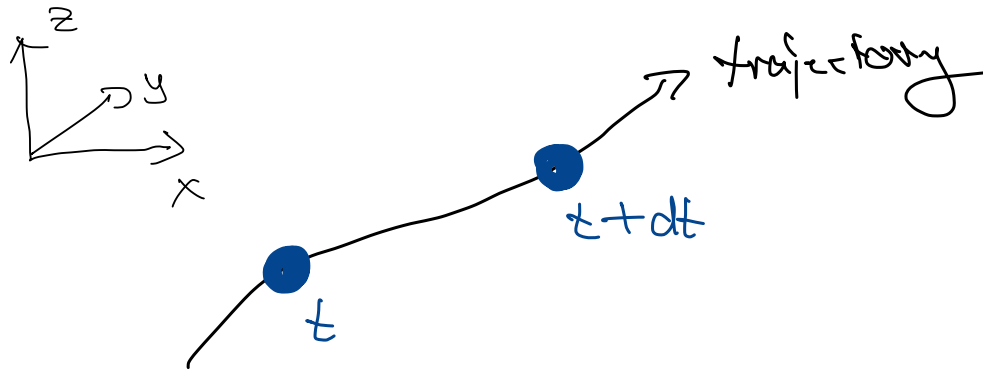


comoving frame

Lagrangian

view point

NB: recall how to compute changes along trajectory



example of number density $n(\vec{x}, t)$

$$dn(\vec{x}, t) = \frac{\partial n}{\partial x_i} dx_i + \frac{\partial n}{\partial t} dt \quad | \frac{d}{dt}$$

$$\frac{dn(\vec{x}, t)}{dt} = \underbrace{\frac{\partial n}{\partial x_i}}_{\vec{\nabla} \cdot \vec{v}} \underbrace{\frac{dx_i}{dt}}_{\vec{v}} + \frac{\partial n}{\partial t} \underbrace{\frac{dt}{dt}}_1 \Rightarrow \boxed{\frac{dn}{dt} = \frac{\partial n}{\partial t} + \vec{v} \cdot \vec{\nabla} n}$$

↳

$$\frac{\partial \rho}{\partial t} + \vec{v} \cdot \vec{\nabla} \rho = \frac{d\rho}{dt} = -\rho \vec{\nabla} \cdot \vec{v}$$

continuity equation

* conservation of momentum: Navier-Stokes equation
Euler equation

$$\partial_t \rho v_i + \partial_j T_{ij} = 0$$

momentum
density

stress-energy tensor

- gives acceleration of fluid element
- on "RHS" we "collect" forces that act on fluid element \rightarrow Newton 3 for fluids!
- let us reformulate to separate acceleration
Lagrangian view point:
 $\frac{d\vec{v}}{dt} = \text{sum of all forces}$
 $=$ pressure + viscose + grav. + magn. forces + ...

$$\underbrace{\frac{d\vec{v}}{dt}}_{\text{acceleration of fluid element}} = \frac{\partial \vec{v}}{\partial t} + \underbrace{\vec{v} \cdot \nabla \vec{v}}_{\text{advection term; quadratic in velocity, non-linear term}} = \Sigma \text{ forces} = \underbrace{-\frac{1}{\rho} \nabla P}_{\text{force due to pressure gradients}}$$

advection term;
quadratic in velocity,
non-linear term
↳ gives rise to
fluid instabilities

~~$$+ \frac{1}{\rho} \left[\eta \nabla^2 \vec{v} + \left(\frac{2}{3}\eta + \frac{\mu}{3} \right) \nabla (\nabla \cdot \vec{v}) \right]$$~~

neglecting viscosity:

Euler's equation

viscosity leads to dissipation

viscous forces: $\nabla^2 \vec{v} \hat{=}$ compression of flow lines; $\nabla (\nabla \cdot \vec{v}) \hat{=}$ bending of flow lines

NB: $\vec{\nabla} \cdot \vec{v} = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \begin{pmatrix} v_x \\ v_y \\ v_z \end{pmatrix} \rightarrow \text{"compression"}$

$\vec{\nabla}(\vec{v} \cdot \vec{v}) = \begin{pmatrix} \partial/\partial x \\ \partial/\partial y \\ \partial/\partial z \end{pmatrix} \left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right) \rightarrow \text{"bending"}$

NB: these equations are obtained as the first three central velocity moments of Boltzmann equation:

$f = \text{phase space density} = f(\vec{q}, \vec{p}, t) = f(\vec{x}, \vec{v}, t)$

$\frac{df}{dt} = \frac{\partial f}{\partial t} + \vec{v} \cdot \vec{\nabla}_x f + \vec{a} \cdot \vec{\nabla}_v f = \cancel{f \dot{}} = 0$ in collisionless Boltzmann eqn.

acceleration: \vec{a}

* when to neglect viscosity?

$\frac{1}{5} \left[\eta \nabla^2 \vec{v} + \left(\frac{2}{3} + \frac{4}{3} \right) \vec{\nabla}(\vec{\nabla} \cdot \vec{v}) \right]$

$\underbrace{\frac{1}{5} \eta \nabla^2 \vec{v}}_{\nu \nabla^2 \vec{v}}$ after small \rightarrow neglect

with kinetic viscosity $\nu = \frac{\eta}{\rho}$

$$[\nu] = \frac{\text{cm}^2}{\text{s}} ; [\eta] = \frac{\text{g}}{\text{cm} \cdot \text{s}}$$

↳ we get for NS equation:

$$\boxed{\frac{d\vec{v}}{dt} = \frac{\partial \vec{v}}{\partial t} + \underbrace{\vec{v} \cdot \nabla \vec{v}}_{\text{advection term}} = \underbrace{+ \nu \nabla^2 \vec{v}}_{\text{viscous term}} - \frac{1}{\rho} \nabla P}$$

approximate:

$$\nabla \sim \frac{1}{l}$$

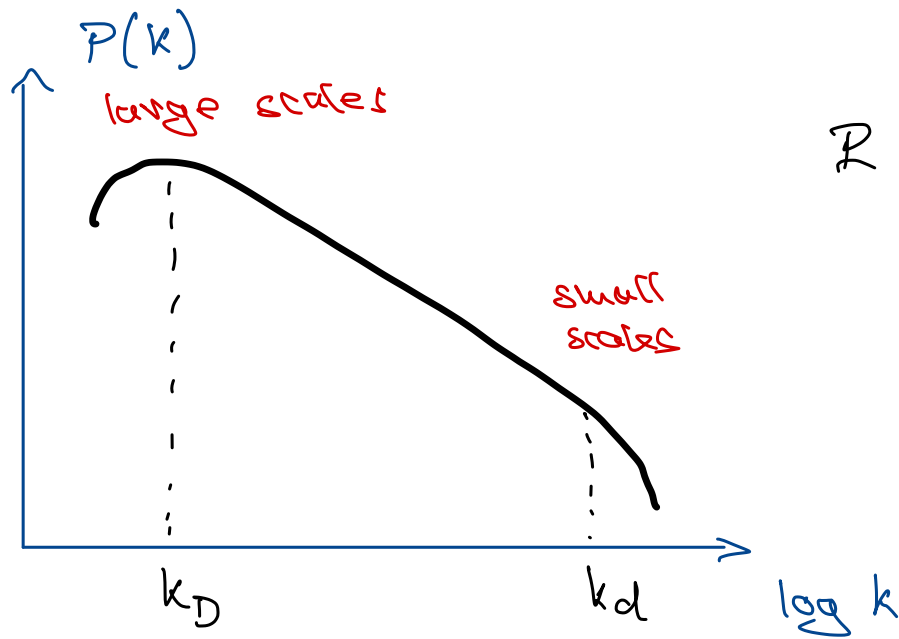
$$\frac{v^2}{l}$$

$$\frac{\nu v}{l^2}$$

↳ definition of Reynolds number

$$Re = \frac{\text{advection}}{\text{dissipation}} = \frac{v^2/l}{\nu v/l^2} = \frac{v \cdot l}{\nu}$$

↳ large Re lead to turbulent instability



$P(k)$ = power spectrum of flow (of its kinetic energy)

k = wave number

driving scale

dissipation scale

$k_d \sim 1/\lambda$ with λ = mean-free path

if $Re \gg 100$

flow is turbulent; advection dominates

if $Re \ll 100$

flow is laminar

if $Re \approx 1$

dissipation regime: $E_{kin} \rightarrow$ thermal energy
($l \sim \lambda$)

* for large R_0 , or scales \rightarrow mean free path
 NS \rightarrow Euler equation:

$$\frac{d\vec{v}}{dt} = \frac{d\vec{v}}{dt} + \vec{v} \cdot \nabla \vec{v} = -\frac{1}{\rho} \nabla P - \nabla \Phi$$

* adding (self)-gravity:

1 grav. force $\vec{F}_g = -\nabla \Phi$



1 introduce additional equation:

$$\nabla^2 \Phi = 4\pi G \rho$$

(for self-gravity; otherwise simply add external force)

1 grav. constant: $G = 6,67 \cdot 10^{-8} \frac{\text{cm}^3}{\text{g s}^2}$

* including magnetic field:

Maxwell equations:

$$\begin{aligned} \vec{\nabla} \cdot \vec{E} &= \frac{\rho}{\epsilon_0} & \vec{\nabla} \cdot \vec{B} &= 0 \\ \vec{\nabla} \times \vec{E} &= -\frac{1}{c} \frac{\partial \vec{B}}{\partial t} & \vec{\nabla} \times \vec{B} &= \frac{4\pi}{c} \vec{j} + \frac{1}{c} \frac{\partial \vec{E}}{\partial t} \end{aligned}$$

force: Lorentz force

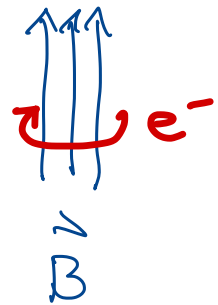
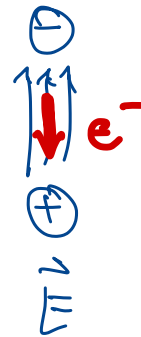
$$\vec{F}_L = q \left(\vec{E} + \frac{1}{c} \vec{v} \times \vec{B} \right)$$

energy density:

$$u = \frac{1}{8\pi} \left(\vec{E}^2 + \vec{B}^2 \right)$$

energy flux: Poynting vector

$$\vec{S} = \frac{c}{4\pi} \left(\vec{E} \times \vec{B} \right)$$



note units in CGS:

$$\therefore [u] = \frac{\text{erg}}{\text{cm}^2} \rightarrow [E] = [B] = \left(\frac{\text{erg}}{\text{cm}^3} \right)^{1/2} = \frac{\text{g}^{1/2}}{\text{cm}^{1/2} \text{s}}$$

recall: $1 \frac{\text{erg}}{\Delta} = 1 \frac{\text{g cm}^2}{\text{s}^2}$

$$\begin{aligned} \therefore \text{force: } [f] &= [q] \cdot [E] \\ \text{with } [f] &= \frac{\text{erg}}{\text{cm}} = \frac{\text{g cm}}{\text{s}^2} \\ &= \text{dyn} \end{aligned} \left. \vphantom{\begin{aligned} \text{force: } [f] &= [q] \cdot [E] \\ \text{with } [f] &= \frac{\text{erg}}{\text{cm}} = \frac{\text{g cm}}{\text{s}^2} \\ &= \text{dyn} \end{aligned}} \right\} \begin{aligned} [q] &= \frac{[f]}{[E]} = \frac{\text{erg/cm}}{(\text{erg/cm}^3)^{1/2}} \\ &= (\text{erg} \cdot \text{cm})^{1/2} = \frac{\text{g}^{1/2} \text{cm}^{3/2}}{\text{s}} \\ &= \text{esu (electrostatic unit)} \end{aligned}$$

elementary charge:

$$e = 4.8 \cdot 10^{-10} \text{ esu}$$

Poynting vector:

$$[S] = \left[\frac{c}{4\pi} \vec{E} \times \vec{B} \right] = \frac{\text{cm}}{\text{s}} \cdot \frac{\text{erg}}{\text{cm}^3} = \frac{\text{erg}}{\text{s}} = \frac{\text{ce}}{\text{s}^2}$$

ideal MHD approximation

- .. strong coupling between neutrals, ions, electrons
- .. good conductivity \rightarrow effective charge neutrality ($\rho = 0$)
- .. frequent collisions ($\lambda_{mp} \ll L$) \rightarrow coupling between n & $e+i$

\hookrightarrow single fluid approximation

note: non-ideal MHD important for star & planet formation

Ohm's law: $\vec{j} = \sigma \left(\vec{E} + \frac{\vec{v}}{c} \times \vec{B} \right)$ with $\sigma =$ conductivity

induction equation: time-evolution of (pre-existing) magnetic field

$$\frac{\partial \vec{B}}{\partial t} = \underbrace{-\frac{c^2}{4\pi\sigma} \nabla^2 \vec{B}}_{\text{diffusion term}} + \underbrace{\nabla \times (\vec{v} \times \vec{B})}_{\text{advection term}}$$

in ideal MHD limit $\sigma \rightarrow \infty$

$$\hookrightarrow \boxed{\frac{\partial \vec{B}}{\partial t} = \nabla \times (\vec{v} \times \vec{B})}$$

1. back to force equation:

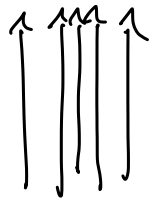
.. force density $\vec{f}_L = \underbrace{nq\vec{E}}_{\text{ideal MHD}} + \frac{\vec{j}}{c} \times \vec{B}$ with $\vec{j} = nq\vec{v}$

.. Maxwell: $\vec{j} = \frac{c}{4\pi} \nabla \times \vec{B}$

↳ together $\rightarrow \vec{f}_L = \frac{1}{4\pi} (\nabla \times \vec{B}) \times \vec{B}$
 $= \frac{1}{4\pi} \underbrace{(B \cdot \nabla) \vec{B}}_{\text{magnetic tension}} + \frac{1}{8\pi} \underbrace{\nabla B^2}_{\text{magnetic pressure}}$



tension



magn. pressure

magnetic pressure:

$P_{\text{mag}} = \frac{B^2}{8\pi} = \text{energy density in } B\text{-field}$

* together: Euler equation in ideal MHD

$$\frac{d\vec{v}}{dt} = \frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \nabla \vec{v} = -\frac{1}{\rho} \nabla (P + \frac{\vec{B}^2}{8\pi}) + \frac{1}{4\pi\rho} (\vec{B} \cdot \nabla) \vec{B} - \nabla \Phi$$

* conservation of energy: $\left[\begin{array}{l} 2^{\text{nd}} \text{ velocity moment} \\ \text{of Boltzmann eqn.} \end{array} \right]$

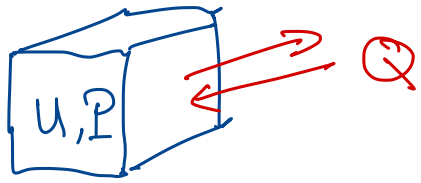
1 in principle, we need to look at energy tensor: $e_{ij} = \frac{1}{2} \rho v_i v_j$

↳ we are mostly interested in the time evolution of internal energy

↳ look at diagonal elements of e_{ij}

↳ $e = \frac{1}{2} \rho v^2$ internal energy density

look at 1st law of thermodynamics



$$dQ = dU + dW$$

heat exchange change of int. energy associated work

$$dQ = T ds$$

$$dW = P dV$$

s = entropy

T = temperature

P = pressure

V = volume

consider specific quantities [per gram]

$$[e] = \frac{\text{erg}}{g}$$

specific internal energy

$$[s] = \frac{\text{erg/k}}{g}$$

entropy

$$\left[\text{NB: } \text{cgs} \rightarrow \text{erg} = \frac{\text{g cm}^2}{\text{s}^2} = 10^{-7} \text{ J} \right]$$

$$\hookrightarrow \frac{de}{dt} = T \frac{ds}{dt} - \frac{dw}{dt}$$

$$w = \frac{W}{M}$$

$$s = \frac{S}{M}$$

$$V = \frac{M}{\rho}$$

$$= T \frac{ds}{dt} - \frac{P}{\rho} \frac{dV}{dt}$$

$$dV = -\frac{M}{\rho^2} d\rho$$

$$= T \frac{ds}{dt} + \frac{P}{\rho^2} \frac{d\rho}{dt}$$

$$= T \frac{ds}{dt} - \frac{P}{\rho} \vec{\nabla} \cdot \vec{v}$$

continuity:

$$\frac{d\rho}{dt} = -\rho \vec{\nabla} \cdot \vec{v}$$

* energy equation:

$$\frac{de}{dt} = \frac{\partial e}{\partial t} + \vec{v} \cdot \vec{\nabla} \cdot e = \underbrace{T \frac{ds}{dt}}_{\textcircled{1} \textcircled{2}} + \frac{P}{\rho^2} \frac{d\rho}{dt}$$

- ① source terms (heating/cooling) are incorporated here
- ② isentropic behavior ($dQ=0$) \rightarrow zero

* this needs a closure!

(more variables in system than equations)

↳ equation of state (EOS)

$$P = P(S, T)$$

↳ for ideal gas:

$$PV = NkT$$

\Rightarrow

$$P = \frac{\rho k T}{\mu \cdot m_p}$$

k = Boltzmann constant
 $= 1,38 \cdot 10^{-16}$ erg/K

V = volume

T = temperature

μ = mean molecular weight

N = number of particles

P = pressure

m_p = proton mass
 $= 1,67 \cdot 10^{-24}$ g

* other ways to describe this relation:

↳ barotropic EOS

$$P = P(\rho)$$

- note: both EOS descriptions can be valid; this implies an implicit relation between ρ and T

↳ polytropic EOS

$$P = K \rho^\gamma$$

$$\gamma = \text{polytropic exponent} = \frac{\text{specific heat at } P=\text{const.}}{\text{specific heat at } V=\text{const.}}$$
$$= \frac{c_p}{c_v}$$

recall: for ideal monoatomic gases

$$c_p = c_v + k \quad (\text{per particle})$$

and we have $c_v = \frac{3}{2} k$ and $c_p = \frac{5}{2} k$

↳ we obtain

$$\gamma = \frac{5}{3}$$

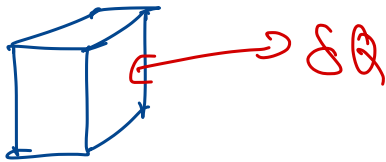
↳ often this is called adiabatic EOS

$$P = K \rho^{5/3}$$

(realized in systems without heat exchange)

↳ isothermal EOS: $\gamma = 1$; $K = c_s^2$

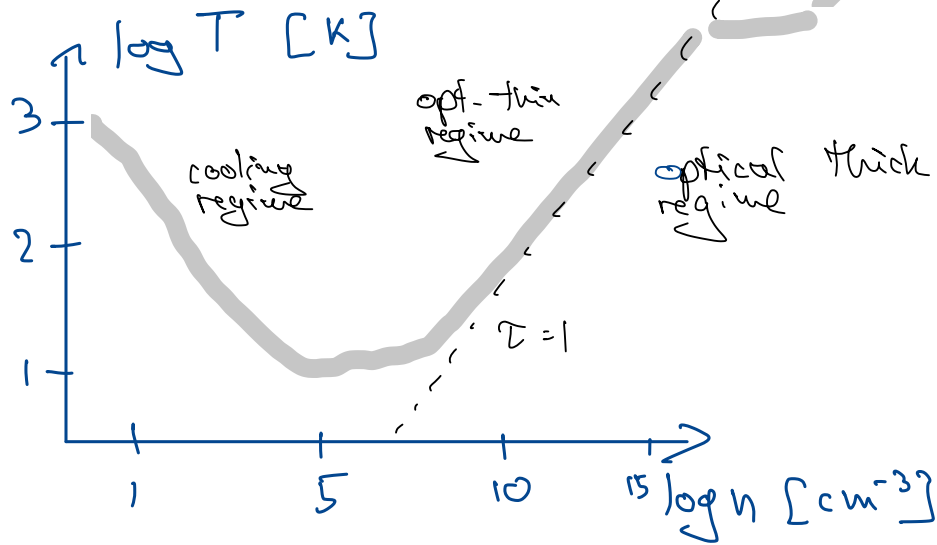
$$P = c_s^2 \rho$$



this can be achieved classically by a perfect coupling of system to external heat bath

in astrophysics: realized by coupling to internal degrees of freedom

example: I_{CO} (interstellar medium)



CO molecule: highly polar \rightarrow strong dipole radiation

implicit relation between T and n :

$$\gamma = 1 + \frac{d \log T}{d \log n}$$

effective equation of state!

* summary:

- we have motivated the equations of magnetohydrodynamics for self-gravitating gas, relevant for stars & planet formation
- but there is much more:
 - radiation: production, coupling to matter, transport
 - chemical & nuclear reactions
 - energy production & heating / cooling
 - cosmic rays
 - etc...
- most of this will be covered in this school

↳ enjoy your time here! 🎉